TITANROB G501 5-F MINI GRABBER

LOW WEIGHT HIGH FORCE RELIABLE



The TitanRob G501 is a five-function hydraulic grabber manipulator made of titanium and developed for Observation- and Light Work Class ROVs. It is a manipulator with enhanced characteristics of weight/power ratio and capabilities: by using titanium as main material, lower weight and more mechanical characteristics are achieved which allows for improved dimensioning.

Resistant, lightweight, and reliable; it's designed for heavy duty ROV works and robotics which require manipulation operations.

The grabber can be operated by any low power (1kW) HPU and solenoids(x5) valve pack fitted in the ROV vehicle.

Typical Operations

- Observation & Light Weight Work ROV
- Fish Farming
- Seabed exploration
- Seabed mining
- Robotics

Features

- Robust construction
- Low weight 13 kg submerged
- Corrosion resistant materials
- High force
- Submersible to 3 000m seawater
- Service- and user friendly
- Cost effective
- Left and right hand configuration
- Low power consumption



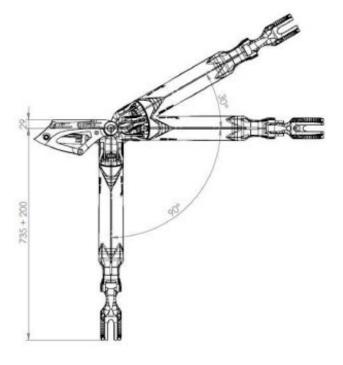
SPECIFICATIONS TITANROB G501 5-F MINI GRABBER

General technical specification

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Type OEM Envirex part no Depth rating Weight (in air / Submerged) Max reach Lift at full extension Max lift Yaw grip Yaw torque Dimension stowed - LxWxH Operation temperature Construction main materials	M kg kg kgf Nm mm °C	TitanRob G501 5-F Mini Grabber TianRob 2214910 (left hand) 3 000 15 / 13 800 80 @ 150bar 100 @ 150bar 250 80 290 x 230 x 783 -5 to 55 Ti6Al4V Titanium AISI 316 SS
Functions Shoulder Azimuth (yaw) Shoulder Pitch Shoulder Extension Jaw Rotate Jaw Opening	° ° mm °	120 (+90 / -30) 110 (+80 / -30) 180 360 continuous 255
Hydraulic requirements Max WP Test pressure Min Flow Max fluid temp. Fluids	bar bar I/min °C	160 200 1,5 55 Mineral based oils (ISO 32, etc)

** HF-Fluids on request / consult supplier.

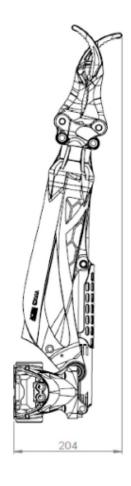
Dimensions

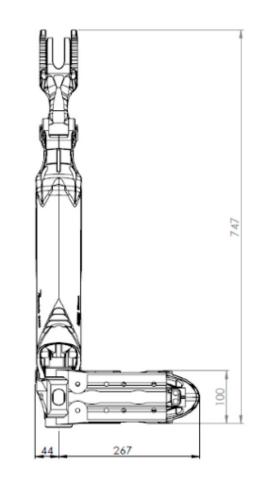




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